

ABSTRACT

A hand-operated feeler ~~comprises~~ includes a rod 8 on a crossed movement table 6, ~~itself~~ mounted on a support 5 fitted with an immobilization ~~means~~ device at a fixed reference as compared to the part to be measured 1; ~~and~~ and a processing unit 7 configured to ~~stores~~ store and ~~processes~~ process the results. Such a device results in rapidly measuring the contours of parts ~~comprising~~ including deep and sunken honeycomb cells.

Figure 1